

Domain Engineering with Concepts

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Domain Engineering

Turning concepts into types and operations

- What are the concepts of a domain
- What is the language we use to express these concepts
- What are the types and operations in this language
- What are the properties of the operations



Story from the trenches: PDE domain

Mathematicians talk about

Vector - 1-indexed array of reals

Matrix - 2-indexed array of reals

changeBasis: Matrix, Vector \rightarrow Vector

dot: Vector, Vector \rightarrow Real,

$$\text{dot}(u,v) = u[0]*v[0] + \dots + u[n-1]*v[n-1]$$

Me:

$\text{dot}(u, \text{changeBasis}(M,v))$

$\text{dot}(\text{changeBasis}(M,u), \text{changeBasis}(M,v)) =$

$\text{changeBasis}(M,u)[0]*\text{changeBasis}(M,v)[0] + \dots + \dots$



Story from the trenches: PDE domain

Mathematicians think

Vector<Basis> - 1-indexed array of reals in given Basis

BasisMap<F,T> - 2-indexed array of reals from F to T

changeBasis: BasisMap<F,T>, Vector<F> -> Vector<T>

dot: Vector<Basis>, Vector<Basis> -> Real

Axiom:

$\text{dot}(u,v) == \text{dot}(\text{changeBasis}(M,u),\text{changeBasis}(M,v))$



Sophus Concepts

Time integration

PDE equation

Tensor abstractions with Basis

Representation: multi-indexed arrays of reals

Scalar fields

Finite Difference, Finite Element, Finite Volume, ...

Representation: huge multi-indexed arrays of reals

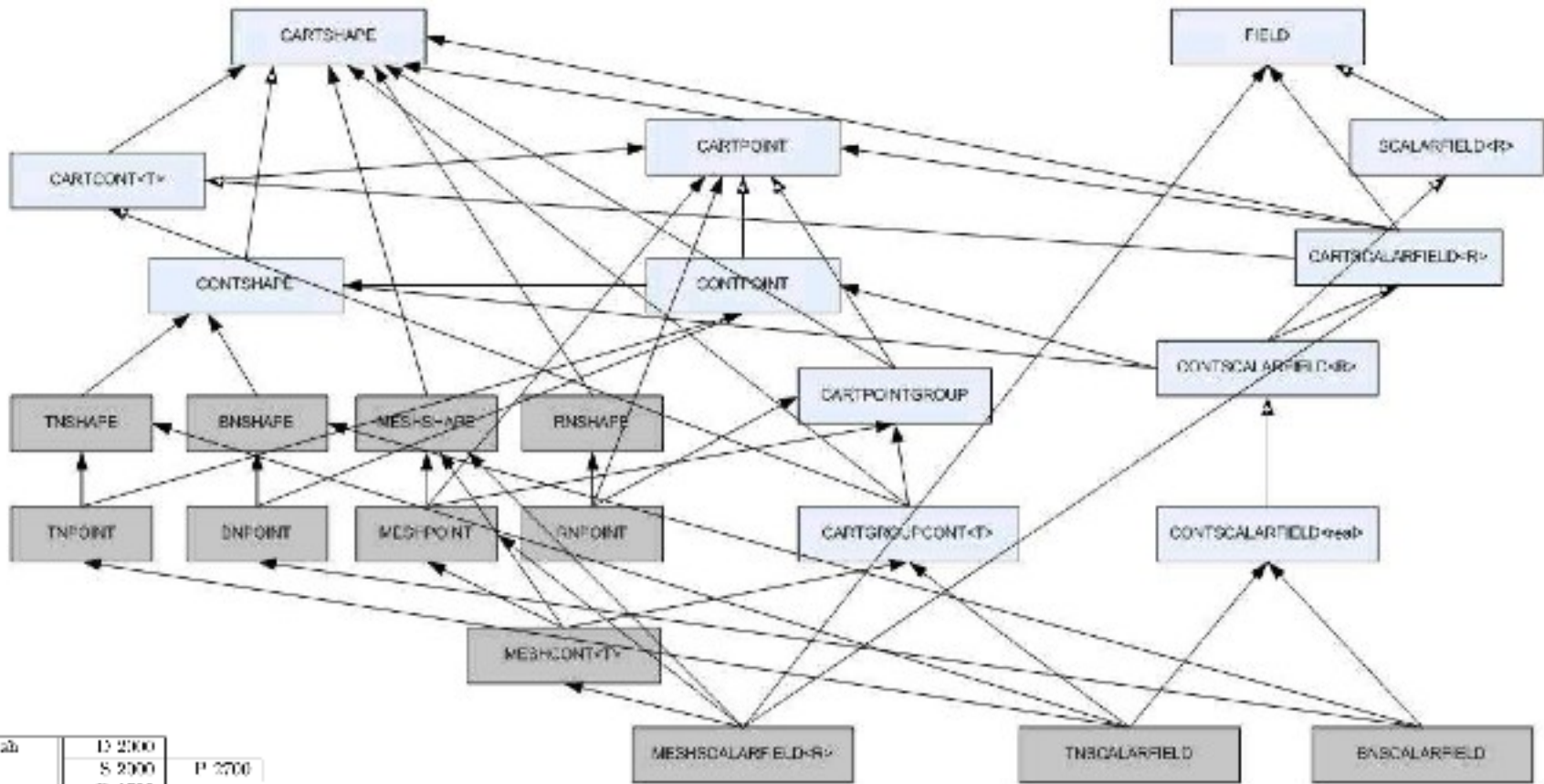
Multi-indexed arrays of reals with collective operations

Sequential layout in memory: per element operations

Parallel distribution: element operations in parallel



Some Sophus Experience



Mesh	D: 2000	S: 2000	P: 2000		
Tn	D: 1700				
	SFD: 1800				
Bn	D: 1500				
Sensor	S: 1800	H: 2100			
	SI: 2800	SIPI: 2800	STA: 3000	CI: 2500	CIPI: 2800
Sensor	SE: 600	PE: 700			

